Diagnostics

gSender 1.4.7

Environment

OS: X11; Linux x86_64 Homing: Disabled Soft Limits: Enabled Home Location: 11 (Front Left) Report Inches: Disabled Stepper Motors: Unlocked

<u>Connectio</u>n

Available Ports:

0: port: /dev/ttyACM0 manufacturer: STMicroelectronics inuse: false Connected Port: /dev/ttyACM0 Baudrate: 115200

Unrecognized Ports:

0:

port: /dev/ttyS0 inuse: false

1:

port: /dev/ttyS1 inuse: false

2:

port: /dev/ttyS2 inuse: false

3:

port: /dev/ttyS3 inuse: false

Machine Profile

ID: 53 Company: Sienci Labs Name: SLB Type: Version: Limits: X Max: 296 Y Max: 228 Z Max: 74 Spindle/Laser: false Laser Mode Enabled: false

GRBL Information

Type: grbIHAL Firmware Version: SuperLongBoard_B5.0.3 MPos: a: 0.000 b: 0.000 c: 0.000 x: 0.000 y: 0.000 z: 0.000 WPos: a: 0.000 b: 0.000 c: 0.000 x: -44.334 y: -20.666 z: 52.382 Sender Status: Modal: NULL Tool: NULL Workflow State: idle Homing Flag: false

Preferences

Jog Presets: Rapid: xyStep: 20 zStep: 10 aStep: 20 xaStep: 20 feedrate: 5000 Normal: xyStep: 5 zStep: 2 aStep: 5 xaStep: 5 feedrate: 3000 Precise: xyStep: 0.5 zStep: 0.1 aStep: 0.5 xaStep: 0.5 feedrate: 1000 Workspace Units: mm Laser: Disabled Rotary: Disabled

EEPROM Values

| Setting | Value |
|---------|-----------|
| \$0 | 5.0 |
| \$1 | 254 |
| \$2 | 0 |
| \$3 | 2 |
| \$4 | 15 |
| \$5 | 8 |
| \$6 | 1 |
| \$8 | 0 |
| \$9 | 1 |
| \$10 | 511 |
| \$11 | 0.010 |
| \$12 | 0.002 |
| \$13 | 0 |
| \$14 | 14 |
| \$15 | 0 |
| \$16 | 0 |
| \$17 | 0 |
| \$18 | 0 |
| \$19 | 0 |
| \$20 | 1 |
| \$21 | 1 |
| \$22 | 79 |
| \$23 | 11 |
| \$24 | 100.0 |
| \$25 | 500.0 |
| \$26 | 125 |
| \$27 | 2.000 |
| \$28 | 0.100 |
| \$29 | 0.0 |
| \$30 | 24000.000 |
| \$31 | 7200.000 |
| \$32 | 0 |
| \$33 | 1000.0 |
| \$34 | 0.0 |
| \$35 | 0.0 |
| \$36 | 100.0 |
| \$37 | 0 |
| \$39 | 1 |
| \$40 | 1 |
| | |

| \$41 | 1 |
|-------|----------|
| \$42 | 2 |
| \$43 | 1 |
| \$44 | 4 |
| \$45 | 3 |
| \$46 | 0 |
| \$47 | 0 |
| \$56 | 5.0 |
| \$57 | 100.0 |
| \$58 | -5.0 |
| \$59 | 500.0 |
| \$60 | 1 |
| \$61 | 3 |
| \$62 | 0 |
| \$63 | 3 |
| \$64 | 0 |
| \$65 | 0 |
| \$70 | 11 |
| \$100 | 1600.000 |
| \$101 | 1600.000 |
| \$102 | 3200.000 |
| \$103 | 19.753 |
| \$110 | 3600.000 |
| \$111 | 3600.000 |
| \$112 | 700.000 |
| \$113 | 8000.000 |
| \$120 | 750.000 |
| \$121 | 750.000 |
| \$122 | 200.000 |
| \$123 | 1000.000 |
| \$130 | 296.000 |
| \$131 | 228.000 |
| \$132 | 74.000 |
| \$133 | 0.000 |
| \$140 | 1900 |
| \$141 | 1900 |
| \$142 | 1700 |
| \$143 | 0 |
| \$150 | 32 |
| \$151 | 32 |
| \$152 | 32 |
| \$153 | 16 |
| \$180 | 150.0 |

| \$181 | 150.0 |
|-------|---------------|
| \$182 | 150.0 |
| \$183 | 150.0 |
| \$190 | 2500.0 |
| \$191 | 2500.0 |
| \$192 | 500.0 |
| \$193 | 5000.0 |
| \$200 | 22.0 |
| \$201 | 22.0 |
| \$202 | 22.0 |
| \$203 | 22.0 |
| \$210 | 35 |
| \$211 | 35 |
| \$212 | 35 |
| \$213 | 50 |
| \$220 | 22.0 |
| \$221 | 22.0 |
| \$222 | 22.0 |
| \$223 | 22.0 |
| \$300 | grblHAL |
| \$301 | 0 |
| \$302 | 192.168.5.1 |
| \$303 | 192.168.5.1 |
| \$304 | 255.255.255.0 |
| \$305 | 23 |
| \$307 | 80 |
| \$308 | 21 |
| \$338 | 7 |
| \$339 | 0 |
| \$340 | 0.0 |
| \$341 | 0 |
| \$342 | 30.0 |
| \$343 | 25.0 |
| \$344 | 200.0 |
| \$345 | 200.0 |
| \$346 | 1 |
| \$370 | 0 |
| \$372 | 0 |
| \$374 | 3 |
| \$375 | 50 |
| \$376 | 1 |
| \$384 | 0 |
| \$392 | 4.0 |

| \$393 | 1.0 |
|-------|-------|
| \$395 | 0 |
| \$398 | 128 |
| \$450 | 1 |
| \$451 | 2 |
| \$452 | 4 |
| \$453 | G4P0 |
| \$454 | G4P0 |
| \$455 | G4P0 |
| \$456 | 0 |
| \$457 | 2 |
| \$458 | 0 |
| \$459 | 2 |
| \$462 | 8192 |
| \$463 | 8193 |
| \$464 | 8451 |
| \$465 | 18 |
| \$466 | 34 |
| \$467 | 1 |
| \$468 | 50.0 |
| \$469 | 60.0 |
| \$470 | 60.0 |
| \$471 | 100.0 |
| \$479 | 4 |
| \$481 | 0 |
| \$484 | 1 |
| \$486 | 0 |
| \$511 | 7 |
| \$512 | 8 |
| \$513 | 5 |
| \$520 | 0 |
| \$521 | 0 |
| \$523 | 0 |
| \$650 | 1 |
| \$651 | 1 |
| \$652 | 0 |
| \$653 | 2 |
| \$654 | 8 |
| \$655 | 0 |
| \$656 | 1 |
| \$657 | 22 |
| \$658 | 7 |
| \$659 | 3 |

| \$660 | 0 |
|-------|---------|
| \$661 | 3 |
| \$662 | 0 |
| \$663 | 41759 |
| \$664 | 0 |
| \$665 | 1 |
| \$666 | 0 |
| \$668 | 0 |
| \$730 | 255.000 |
| \$731 | 0.000 |
| \$733 | 1000.0 |
| \$734 | 0.0 |
| \$735 | 0.0 |
| \$736 | 100.0 |
| \$741 | 0.000 |
| \$742 | 0.000 |
| \$743 | 0 |

Recent Alarms

6/16/2024, 6:43:02 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: (JuneFusionTest-v2) Controller: grbIHAL

6/9/2024, 4:17:02 PM

EStop asserted. Clear and reset Input: N/A Controller: grbIHAL

6/7/2024, 4:15:17 PM

EStop asserted. Clear and reset Input: N/A Controller: grblHAL

6/3/2024, 3:37:52 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

6/3/2024, 2:49:31 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

6/3/2024, 2:48:28 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring. Input: N/A Controller: grbIHAL

6/1/2024, 4:10:34 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

6/1/2024, 4:08:30 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: \$hz Controller: grbIHAL

6/1/2024, 4:07:21 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

6/1/2024, 4:05:22 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

6/1/2024, 3:57:17 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

5/31/2024, 4:07:36 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/31/2024, 3:49:56 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/31/2024, 3:49:02 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/31/2024, 3:47:36 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/31/2024, 3:46:52 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/31/2024, 3:46:23 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

5/29/2024, 7:35:48 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/29/2024, 7:34:15 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

5/29/2024, 7:16:39 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/29/2024, 7:13:51 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/29/2024, 7:13:23 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

5/29/2024, 7:13:01 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel,

decreasing pull-off distance, or check wiring. Input: N/A Controller: grbIHAL

5/29/2024, 2:12:06 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

5/29/2024, 1:31:12 PM EStop asserted. Clear and reset Input: N/A Controller: grbIHAL

5/29/2024, 1:30:55 PM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grbIHAL

5/28/2024, 11:58:00 AM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: N/A Controller: grblHAL

5/28/2024, 11:57:32 AM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: N/A Controller: grbIHAL

5/28/2024, 11:56:27 AM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring. Input: N/A Controller: grbIHAL

5/28/2024, 11:55:56 AM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: g1 y100 f5000 Controller: grblHAL

5/28/2024, 11:49:57 AM

Homing fail. Could not find limit switch within search distances. Try increasing max travel, decreasing pull-off distance, or check wiring.

Input: N/A Controller: grblHAL

5/28/2024, 11:33:46 AM

Reset while in motion. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: G1 X200 f5 Controller: grblHAL

5/26/2024, 7:48:22 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z-100 f5000 Controller: grblHAL

5/26/2024, 7:33:37 PM EStop asserted. Clear and reset Input: M8 Controller: grbIHAL

5/26/2024, 7:27:25 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z10 f5000 Controller: grblHAL

5/26/2024, 7:27:06 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z49 f5000 Controller: grbIHAL

5/26/2024, 7:26:46 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z50 f5000 Controller: grblHAL

5/26/2024, 7:26:32 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z60 f5000 Controller: grblHAL

5/26/2024, 7:25:51 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z50 f5000 Controller: grbIHAL

5/26/2024, 5:14:22 PM EStop asserted. Clear and reset Input: N/A Controller: grbIHAL

5/26/2024, 5:11:55 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 X-30 F2500 Controller: grbIHAL

5/26/2024, 5:11:32 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 X-60 F2500 Controller: grblHAL

5/26/2024, 5:11:07 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 X-70 F2500 Controller: grblHAL

5/26/2024, 5:10:09 PM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: N/A Controller: grblHAL

5/26/2024, 5:09:39 PM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: N/A Controller: grblHAL

5/26/2024, 5:08:59 PM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing

is highly recommended. Input: N/A Controller: grblHAL

5/26/2024, 5:08:45 PM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: N/A Controller: grblHAL

5/26/2024, 5:07:50 PM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: N/A Controller: grblHAL

5/26/2024, 5:07:21 PM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: G1 Y-100 F5000 Controller: grbIHAL

5/26/2024, 4:58:14 PM

Homing fail. Pull off travel failed to clear limit switch. Try increasing pull-off setting or check wiring.

Input: N/A Controller: grblHAL

5/26/2024, 4:57:56 PM

Homing fail. Pull off travel failed to clear limit switch. Try increasing pull-off setting or check wiring.

Input: N/A Controller: grblHAL

5/26/2024, 4:57:45 PM

Homing fail. Pull off travel failed to clear limit switch. Try increasing pull-off setting or check wiring.

Input: N/A Controller: grblHAL

5/26/2024. 4:56:58 PM

Hard limit has been triggered. Machine position is likely lost due to sudden halt. Re-homing is highly recommended.

Input: \$\$ Controller: grbIHAL

5/25/2024, 3:12:49 PM

EStop asserted. Clear and reset Input: N/A Controller: grblHAL

5/19/2024, 6:27:55 PM EStop asserted. Clear and reset Input: N/A Controller: grblHAL

5/18/2024, 1:12:08 PM

Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z70 F5000 Controller: Grbl

5/18/2024, 1:11:06 PM Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked.

Input: G1 Z70 F5000 Controller: Grbl

5/18/2024, 12:58:45 PM Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked. Input: G1 Y225 F5000 Controller: Grbl

3/23/2024, 2:14:44 PM Soft limit alarm. G-code motion target exceeds machine travel. Machine position retained. Alarm may be safely unlocked. Input: S18400 M3 Controller: Grbl

Recent Errors

6/3/2024, 3:36:09 PM Missing the expected G-code word value or numeric value format is not valid. Input: N/A Controller: Grbl

6/1/2024, 4:08:11 PM Missing the expected G-code word value or numeric value format is not valid. Input: HZ Controller: grbIHAL

6/1/2024, 4:08:11 PM Missing the expected G-code word value or numeric value format is not valid. Input: HZ Controller: grbIHAL

5/26/2024, 4:58:38 PM Feed rate has not yet been set or is undefined. Input: G1 X100 Controller: grbIHAL

5/19/2024, 7:04:41 PM Missing the expected G-code word value or numeric value format is not valid. Input: \$\$ Controller: Grbl

5/18/2024, 12:44:40 PM Feed rate has not yet been set or is undefined. Input: G1 X1 Controller: Grbl

Terminal History

gSender - [grblHAL] Connected to /dev/ttyACM0 with a baud rate of 115200 [VER:1.1f.20230917:] \$\$ [OPT:VNMPZHS+2,128,1024,4,0] [NEWOPT:ENUMS,RT+,HOME,ES,SED,ETH,FTP,TMC=7,SD,YM] [FIRMWARE:grblHAL] [NVS STORAGE:*EEPROM] [FREE MEMORY:133K] [DRIVER:STM32F412] [DRIVER VERSION:230828] [BOARD:SuperLongBoard_B5.0.3] [AUX IO:3,4,0,0] [WIZCHIP:W5500] [IP:192.168.5.1] [PLUGIN:Trinamic v0.12] [PLUGIN:MODBUS v0.14] [PLUGIN:HUANYANG VFD v0.11] [PLUGIN:HUANYANG P2A VFD v0.10] [PLUGIN:Durapulse VFD GS20 v0.05] [PLUGIN: Yalang VFD YL620A v0.02] [PLUGIN:MODVFD v0.03] [PLUGIN:H-100 VFD v0.03] [PLUGIN:SLB Laser PWM switch v0.01] [SPINDLE:SLB_SPINDLE] [PLUGIN:SIENCI Indicator Lights v1.0] [PLUGIN:Bootloader Entry v0.01] [PLUGIN:Macro plugin v0.03] [PLUGIN:SLB Probing v0.01] [PLUGIN:SwitchBank plugin v0.02] [PLUGIN:SDCARD v1.10] [PLUGIN:FS macro plugin v0.05] ok \$0=5.0 (Step pulse time, \$4) \$1=254 (Step idle delay, ms) \$2=0 (Step pulse invert, mask) \$3=2 (Step direction invert, mask) \$4=15 (Invert step enable pin, boolean) \$5=8 (Invert limit pins, boolean) \$6=1 (Invert probe pin, boolean) \$8=0 \$9=1 \$10=511 (Status report options, mask) \$11=0.010 (Junction deviation, mm) \$12=0.002 (Arc tolerance, mm) \$13=0 (Report in inches, boolean) \$14=14 15=0\$16=0 \$17=0 \$18=0 \$19=0 \$20=1 (Soft limits enable, boolean) \$21=1 (Hard limits enable, mask) \$22=79 (Homing cycle enable, mask) \$23=11 (Homing direction invert, mask) \$24=100.0 (Homing locate feed rate, mm/min) \$25=500.0 (Homing search seek rate, mm/min) \$26=125 (Homing switch debounce delay, ms) \$27=2.000 (Homing switch pull-off distance, mm) \$28=0.100 (G73 pull-off distance, mm) \$29=0.0 (Step Pulse Delay, \$4) \$30=24000.000 (Maximum spindle speed, rpm) \$31=7200.000 (Spindle Mode,) \$32=0 (Laser-mode enabled as spindle, boolean) \$33=1000.0 (Spindle Frequency, Hz) \$34=0.0 (Spindle Duty Cycle, %) \$35=0.0 (Minimum spindle speed, %) \$36=100.0 (Maximum spindle speed, %) \$37=0 (Deenergized Steppers, %)

\$39=1 (Printable Command Characters, boolean) \$40=1 (Soft Limits Jogging, boolean) \$41=1 \$42=2 \$43=1 (Homing Locate Cycle,) \$44=4 (Axis Mask,) \$45=3 (Axis Mask,) \$46=0 (Axis Mask,) \$47=0 (Axis Mask,) \$56=5.0 \$57=100.0 \$58 = -5.0\$59=500.0 \$60=1 (Restore Default Overrides, boolean) \$61=3 (Ignore Safety Door Signal, boolean) \$62=0 (Sleep Function, boolean) \$63=3 (Disable Laser on Hold, boolean) \$64=0 (Alarm on Startup, boolean) \$65=0 (Allow Feedrate Override, boolean) \$70=11 (Network Service,) \$100=1600.000 (X-axis travel resolution, step/mm) \$101=1600.000 (Y-axis travel resolution, step/mm) \$102=3200.000 (Z-axis travel resolution, step/mm) \$103=19.753 \$110=3600.000 (X-axis maximum rate, mm/min) \$111=3600.000 (Y-axis maximum rate, mm/min) \$112=700.000 (Z-axis maximum rate, mm/min) \$113=8000.000 \$120=750.000 (X-axis acceleration, mm/sec^2) \$121=750.000 (Y-axis acceleration, mm/sec^2) \$122=200.000 (Z-axis acceleration, mm/sec^2) \$123=1000.000 \$130=296.000 (X-axis maximum travel, mm) \$131=228.000 (Y-axis maximum travel, mm) \$132=74.000 (Z-axis maximum travel, mm) \$133=0.000 \$140=1900 \$141=1900 \$142=1700 \$143=0 \$150=32 \$151=32 \$152=32 \$153=16 \$180=150.0 \$181=150.0 \$182=150.0 \$183=150.0 \$190=2500.0 \$191=2500.0 \$192=500.0 \$193=5000.0 \$200=22.0 \$201=22.0 \$202=22.0 \$203=22.0

```
$210=35
$211=35
$212=35
$213=50
$220=22.0
$221=22.0
$222=22.0
$223=22.0
$300=grbIHAL
$301=0
$302=192.168.5.1
$303=192.168.5.1
$304=255.255.255.0
$305=23
$307=80
$308=21
$338=7
$339=0
$340=0.0 (Spindle at speed tolerance, %)
$341=0 (Manual tool change mode, )
$342=30.0 (Probing distance, mm)
$343=25.0 (Probing slow feed rate, mm/min)
$344=200.0 (Probing seek feed rate, mm/min)
$345=200.0
$346=1
$370=0
$372=0
$374=3
$375=50
$376=1
$384=0
392=4.0
$393=1.0
$395=0
$398=128
$450=1
$451=2
$452=4
$453=G4P0
$454=G4P0
$455=G4P0
$456=0
$457=2
$458=0
$459=2
$462=8192
$463=8193
$464=8451
$465=18
$466=34
$467=1
$468=50.0
$469=60.0
$470=60.0
$471=100.0
$479=4
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\$481=0 \$484=1 \$486=0 \$511=7 \$512=8 \$513=5 \$520=0 \$521=0 \$523=0 \$650=1 \$651=1 \$652=0 \$653=2 \$654=8 \$655=0 \$656=1 \$657=22 \$658=7 \$659=3 \$660=0 \$661=3 \$662=0 \$663=41759 \$664=0 \$665=1 \$666=0 \$668=0 \$730=255.000 \$731=0.000 \$733=1000.0 \$734=0.0 \$735=0.0 \$736=100.0 \$741=0.000 \$742=0.000 \$743=0 ok ok ok ok ok 0 - SLB_SPINDLE, enabled as spindle 0, DIV, current 1 - Huanyang v1 2 - Huanyang P2A 3 - Durapulse GS20 4 - Yalang YS620 5 - MODVFD, enabled as spindle 3, SDV 6 - H-100 7 - SLB_LASER, enabled as spindle 1, DIRV ok \$X ok

G-Code File

No File Loaded